## Intelligent display instrument APOSYS 02- xx - x - x

## TECHNICAL DOCUMENTATION



Producer:
 measurement \& control
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## 1. Introduction

APOSYS 02 is intelligent 4 points display instrument controlled by microprocessor with possibility of signalling 2 limit values.

## 2. Description

### 2.1 Front panel



## 1 - Display

Display shows measured value. At parameters programming the display provides lucid report.

## 2 - The check lights of outputs state

The check lights „OUT1" and „OUT2" 4 indicate the state of outputs relays by this way: the check light is lighting - output is switch-on, the check light don't lights - output is switch-off.

## 3 - - The check light „MODE*

The check light „MODE" indicate presence in the programming menu.

## 4 - Key „MODE*

Key „MODE" is for input to programming of parameters and for confirmation of setting dates.

## 5 - Setting keys

Keys are for listing in a parameters selection and for numbers dates setting at programming. At the key keeping the listing or setting run faster. When you press both keys at same time the setting parameter is deleted.

### 2.2 Input part

On inputs terminals blocks of the instrument is possible to connect the sensor Pt100, Ni1000/6180ppm, resistive temperature transmitter Mesit (P1-8, LUN 1356-8 till LUN 13588 with resistance $0^{\circ} \mathrm{C}=90,1 \Omega$ and $100^{\circ} \mathrm{C}=129,8 \Omega$ ), thermocouple (J, K, E, T, R, S), current signal ( $4-20 \mathrm{~mA}, 0-20 \mathrm{~mA}$ ) or voltage signal ( $0-10 \mathrm{~V}$ ). Changes of a type of the input signal is possible achieve by apparatus keypad or by program PA 02a. From production is the instrument set to input value which is shows in the chart of limit values on page 16.

### 2.3 Output part

Output elements are two miniature relays with max. loading 250 VAC, 2 A.
Relay contacts are protected by varistors. For switching of inductive loading is recommended ,for increase of reliability and decrease of interference, to connects for corresponding contacts anti-jamming RC networks (for example $0,1 \mu \mathrm{~F}+220 \Omega$ ).

Warning: Connected varistors are defined for max. working voltage 250 Vef. At switching some motors in a single-phase connecting with a capacitor, for phase shift, can make it on winding connected through the capacitor permanent increasing the working voltage over setting of value allowable varistors voltage.

### 2.4 Signalling

The instrument is equip with the function of signalling of 2 limits values. For both values is possible to select the function (on/off after overrun of the required value). Both eventual states are demonstrate on the diagram:


### 2.5 Technical dates

Power supply

Power input
Fuse

Display

Decimal point
Input signal:
sensor Pt100 by DIN IEC 751/A2
sensor Ni1000/6180ppm
thermocouple „J"
thermocouple „K"
thermocouple „E"
thermocouple „T"
thermocouple „R"
thermocouple „S"
current signal
voltage signal
resistive temperature transmitter MESIT

APOSYS 02-xx-1=1/N/PE - 230 VAC(+10-15\%) 50 Hz
APOSYS 02-xx-2=24 VDC ( $+10-15 \%$ )
APOSYS 02-xx-3= 24 VAC ( $+10-15 \%$ ) 50 Hz max. 5 VA
for power supply $230 \mathrm{VAC}-0,05 \mathrm{~A}$ (T 50 mA )
for power supply $24 \mathrm{VDC}-1,25 \mathrm{~A}$ (T $1,25 \mathrm{~A}$ )
for power supply $24 \mathrm{VAC}-0,63 \mathrm{~A}$ ( T 630 mA )
-999~0~9999
red 4 point LED with high intensity of light or green 4 point LED with high intensity of light height of marks 10 mm setting by program
$-80 \sim 800^{\circ} \mathrm{C}$
$-50 \sim 200^{\circ} \mathrm{C}$
$-200 \sim 1200^{\circ} \mathrm{C}$
$-200 \sim 1300^{\circ} \mathrm{C}$
$-200 \sim 1000^{\circ} \mathrm{C}$
$-200 \sim 400^{\circ} \mathrm{C}$
$-50 \sim 1700^{\circ} \mathrm{C}$
$-50 \sim 1700^{\circ} \mathrm{C}$
$4 \sim 20 \mathrm{~mA}, 0 \sim 20 \mathrm{~mA}$
$0 \sim 10 \mathrm{~V}, 0 \sim 70 \mathrm{mV}$
$-50 \sim 300^{\circ} \mathrm{C}$ (,,P1-8, LUN 1356-8, LUN 1357-8,
LUN1358-8" measuring accuracy $0,5 \%$ )

Compensation of thermocouples comparison ends:

Inner
outer
accuracy $0,5^{\circ} \mathrm{C}$ at temp. $20^{\circ} \mathrm{C}$
temperature coefficient $50 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$
$20^{\circ} \mathrm{C}, 50^{\circ} \mathrm{C}$ or $70^{\circ} \mathrm{C}$ setting by program
Outputs:
switching
data

Temperature coefficient
Measuring accuracy
Speed
Resolution
Calibration
Data redundancy
Type of apparatus
Dimensions
Mounting hole in panel
Keyboard

2 x relay $250 \mathrm{VAC}, 2 \mathrm{~A}$
RS 485, bidirectional communication, speed 9600
Baud
11 transmission bits, communication master-slave
$25 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$
$\pm 0,15 \%$ from range $\pm 1$ digit
3 measurement per second
by decimal point state, max. 0,01
at $25^{\circ} \mathrm{C}$ and $40 \%$ r.h.
electrically (EEPROM)
panel
$96 \times 48 \times 119 \mathrm{~mm}$
$90,5 \times 43,5 \mathrm{~mm}$ (with holes $\varnothing 3 \mathrm{~mm}$ in angles)
foil 3 keys

## Weight

Operating temperature
Steady time
Coverage
Bonding
Source
Electromagnetic Compatibility

Seismic proof
$0,4 \mathrm{~kg}$
$0 \sim 60^{\circ} \mathrm{C}$
to 5 min after switch-on
IP 54 (front panel)
terminal block (max. section $2,5 \mathrm{~mm}^{2}$ )
for power supply of the sensor up to 25 mA
ČSN EN 50081-2
ČSN EN 50082-1
ČSN IEC 980:1993, čl. 6

### 2.6 Dimensions



### 2.7 Mounting instructions

The controller handle in the mounting hole with help two holders.
Wires are connected to screw connectors on the rear panel of the controller. Connectors are as 3 single taking down construction blocks: connector 1-6-block of inputs and c communication, connector 7-10-block of relays outputs, connector 11, 12 - block of power supply. Every block of connectors is possible to take down back from the controller. Wires are possible to connect to taking down blocks and then connect all blocks to the controller.

### 2.8 Apparatus connecting

Switch or trip switch must be:

- building installation components
- in immediate apparatus neighbourhood
- operator accessible
- tagged as isolating system element


## WARNING:

If you use this apparatus by another way than define producer could be the protection provided by apparatus corrupted.


Inputs signale


### 2.9 Connecting of terminal block

## WARNING:

### 2.10 Measure ranges of inputs quantities

| Type | Range |
| :---: | :---: |
| Sensor Pt100 | $-80 \sim 800^{\circ} \mathrm{C}$ |
| Sensor Ni1000/6180 ppm | $-50 \sim 200^{\circ} \mathrm{C}$ |
| Thermocouple J | $-200 \sim 1200^{\circ} \mathrm{C}$ |
| Thermocouple K | $-200 \sim 1300^{\circ} \mathrm{C}$ |
| Thermocouple E | $-200 \sim 1000^{\circ} \mathrm{C}$ |
| Thermocouple T | $-200 \sim 400^{\circ} \mathrm{C}$ |
| Thermocouple R | $-50 \sim 1700^{\circ} \mathrm{C}$ |
| Thermocouple S | $-50 \sim 1700^{\circ} \mathrm{C}$ |
| Current signal 4 $\sim 20 \mathrm{~mA}$ | Optional |
| Current signal 10 $\sim 20 \mathrm{~mA}$ | Optional |
| Voltage signal 0 $\sim 10 \mathrm{~V}$ | Optional |
| Resistive temperature transmitter P1-8, LUN |  |
| $1356-8$, LUN 1357-8, LUN 1358-8 | $-50 \sim 300^{\circ} \mathrm{C}$ |

### 2.11 Inner inputs connecting


2.12 Example of threewires current sensor 4.. 20 mA connecting


### 2.13 Connecting of interface field

In the interface field is necessary to set by delivered bonds the type of elect input signal optionally lockout of dates or ending of communication line RS 485. The interface field is allowable after extraction of bonds 1-6.


Option of bonds setting:

| Type | Bonds adjusting |
| :---: | :---: |
| Sensor Pt100 | K1, K2, K3 |
| Sensor Ni1000/6180 ppm | K1, K2, K3 |
| Thermocouple J, K, E, T, R, S | K2, K4 |
| Current signal $4 \sim 20 \mathrm{~mA}$ (passive) | K2, K5, K6 |
| Current signal 0(4) $\sim 20 \mathrm{~mA}$ (active) | K2, K4, K5 |
| Resistive temperature transmitter P1-8, LUN |  |
| 1356-8, LUN 1357-8, LUN 1358-8 | K1, K2, K3 |
| Voltage signal 0 $\sim$ 10 V | K4, K5 |
| Lockout of dates | K7 |
| Ending of line RS 485 | K8 |

At selecting of the type of inputs signal by program PA 02 is necessity to respect the setting of the interface field.

## 3. The programming

In the programming mode is possible to set optional parameters of the controller. For using of the controller is necessity to adapt the controller to concrete user application by setting of the required parameters. Standard values are in the programming mode setting by producer. And they are show in a limit values chart (page 16). After program escape in the menu END by key MODE will dates writing run over.

As long as in the programming course do not be pressed the arbitrary key during 1 minute the controller automatically come over to main menu without setting parameters record (function TIME OUT).

## Warning :

Before programming is necessity to check if is taking out the bond K7-for lockout of dates. After finish of programming is possible to protect parameters against overwriting by setting of bond K7, this means that parameters is possible to change at discretion, but after break-and-make of power supply appears parameters set before interdict of overwriting.

### 3.1 Meaning of parameters



## Operating menu

By the key „MODE" press you enter to programming.

## ALA1

limit value for output out1

## ALA2

limit value for output out2

## HYS1

hysteresis of switching for output out1

## HYS2

hysteresis of switching for output out2

## OUT1

function of output out1 (-OR- after achievement of limit switch-off, -NOR after achievement of limit switch-on)

## OUT2

function of output out2 (-OR- after achievement of limit switch-off, -NOR after achievement of limit switch-on)

## STRS

beginning of the measuring range (start sensor), valid only for current and voltage signals. For resistive and thermocouple sensors it is not shows

## ENDS

end of the measuring range (end sensor), valid only for current and voltage signals. For resistive and thermocouple sensors it is not shows

## OFFS

shift of measured value

## COMP

type of thermocouple compensation - valid only for thermocouple! (-NO- without compensation, TS-- compensation for temperature of clamps, 20,50 or $70^{\circ} \mathrm{C}$ )

## FILT

integrating filter for suppression of input signal changes
_DP_
decimal point position

## SENS

type of input signal:

| U- | thermocouple „J" |
| :---: | :---: |
| CRRL | thermocouple „K" |
| $E^{-}$ | thermocouple „E" |
| $T$ | thermocouple „T" |
| R | thermocouple „R" |
| 5 | thermocouple „S" |
| PT | sensor Pt100 |
| M1_6 | sensor Ni1000/6180 |


| $4 \_20$ | CURRENT signal $4-20 \mathrm{~mA}$ |
| :--- | :--- |
| $0 \_20$ | CURRENT signal $0-20 \mathrm{~mA}$ |
| $0-10$ | voltage signal $0-10 \mathrm{~V}$ |
| MES | resistive sensor |

At selecting of the type of inputs signal is necessity to respect the setting of the interface field (see connecting of interface field page Chyba! Záložka není definována.).


## HESL

access code - from production is set „0". This means that access to programming mode is not under a password. If you set a arbitrary number password, this will be required always at access to programming. At ignorance of the password is possible to access to code „,555".

## ER-1 (ER-2)

state of the output relay 1(2) at failure of input sensor
$(-\mathrm{OFF}=$ at failure is the output switch-off, $-\mathrm{ON}-=$ at failure is the output switch-on)
by press of the key „MODE" you will finish the programming.

Attention for TIME OUT function. At TIME OUT function will not save set parameters in the programming mode.

## 4. Parameters limit values

| Code | Importance | Limit values | From production |
| :---: | :---: | :---: | :---: |
| ALA1 | limit value 1 | -999 to 9999 | 0.0 |
| ALA2 | limit value 2 | -999 to 9999 | 0.0 |
| HYS1 | switching hysteresis output 1 | 0 to 9999 | 0.0 |
| HYS2 | switching hysteresis output 2 | 0 to 9999 | 0.0 |
| OUT1 | output 1 function | -OR-, -NOR | -OR- |
| OUT2 | output 2 function | -OR-, -NOR | -OR- |
| STRS | beginning of measurement range | -999 to 9999 |  |
| ENDS | end of measurement range | -999 to 9999 |  |
| OFFS | offset | -999 to 9999 | 0.0 |
| -DP- | decimal point | 0., 0.0, 0.00 | 0.0 |
| SENS | sensor type | thermocouple J,K,E,T,R,S Pt100 Ni1000/6180ppm 4 to 20 mA 0 to 20 mA 0 to 10 V resistive temperature transmitter P1-8, LUN $1356-8$, LUN 1357- 8, LUN 1358-8 |  |
| CoMP | type of thermocouple compensation | NO, temp. of clamps, $20^{\circ} \mathrm{C}, 50^{\circ} \mathrm{C}, 70^{\circ} \mathrm{C}$ | temp. of clamps |
| FILT | integrating filter | 0 to 10 | 0 |
| HESL | access password | -999 to 9999 | 0 |
| ER-1 | output relay 1 state at sensor failure | -OFF, -ON- | -OFF |
| ER-2 | output relay 2 state at sensor failure | -OFF, -ON- | -OFF |

## The input sensor setting from the production The chart of failure sates

The instrument is provide with failure states signalling. At the sensor failure is possible in the menu ER-1 (ER-2) select the output relays state (-OFF = switch-off, -ON- = switch-on).

| Type of sensor | signalling E --- | signalling E --- |
| :--- | :--- | :--- |
| Pt100, Ni1000 | short circuit of sensor | disconnection of sensor |
| Thermocouple J, K, E, T, R, S | - | disconnection of sensor |
| $0 \sim 20 \mathrm{~mA}$ | - | $>22 \mathrm{~mA}$ |
| $4 \sim 20 \mathrm{~mA}$ | $<3 \mathrm{~mA}$ | $>22 \mathrm{~mA}$ |
| $0 \sim 10 \mathrm{~V}$ | - | $>10,5 \mathrm{~V}$ |

## 5. The communication protocol description

Communication protocol agree with protocol PROFIBUS layer 2. Data part (layer 7) implemented the protocol.
Communication is of the type master - slave and enable the two-ways communication between stations. The communication use the interface RS 485.

## Telegram mark (UART - Character)

Protocol:


Every UART - character have 11 bits, and so 1 th start-bit (ST) with signal logic " 0 ", 8 inform bits (I), 1 parity bit for even parity ( P ) with signal logic "1" and 1 stop-bit (SP) with signal logic " 1 ".Transmit speed is 9600 Bd .

## Communication conditions:

Communications are initiate by superior communication participant on a principle request answer. This principle allows addition of bigger numbers of participants to superior system on the interface RS-485.Controllers and sensors work as a slave participant .
From time aspect is necessary to keep following conditions:
a) among single bits transmit from superior system have to be shorter delay than treble of a time necessary for transmit of the one bit.
b) among received answer and transmitted next message have to be rest on the line longer than treble of a time necessary for transmit of the one bit.
c) If the receive side detect a defect of link protocol (frame error, parity error, impassableness link, breach of listed above conditions), or a failure in the communication protocol (failure start parity mark, or finish mark, length of a telegram), the receive side the message unwork and not even answer. In a case of non-performance request for transmission or for logging (the instrument contains no dates), failure message is transmitted with SD1 and $\mathrm{FC}=2$ (negative confirmation).
d) among last bit of the transmitted message and the first bit of the received answer is delay at minimum same as the time necessary for transmit of one bit..

## LAYER 2

## Formats of telegrams with compact length without data pole:

a) question

| SD1 | DA | SA | FC | FCS | ED |
| :--- | :--- | :--- | :--- | :--- | :--- |

b) answer

| SD1 | DA | SA | FC | FCS | ED |
| :--- | :--- | :--- | :--- | :--- | :--- |

## Format of telegrams with compact length

Telegram starts with SD1 and FC=0x69 and finish by finish mark ED.
Positive answer is the telegram with compact length with $\mathrm{FC}=0$. Negative answer $\mathrm{FC}=2$.

## Example of setting format of telegram with compact length without dates pole:

REQUEST
Number of transmitting marks: 6
$\begin{array}{llllll}10 & 02 & 04 & 69 & 6 F & 16\end{array}$
ANSWER
Number of receiving marks:

```
10}040200 06 16 
```


## Formats of telegrams with variable length of information pole:

a) question

| SD2 | LE | LEr | SD2 | DA | SA | FC | DATA | FCS | ED |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

b) answer

| SD2 | LE | LEr | SD2 | DA | SA | FC | DATA | FCS | ED |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

## Importance of used symbols

| SD1 | frame start (Start Delimiter), code 10H |
| :--- | :--- |
| SD2 | frame start (Start Delimiter), code 68H |
| LE | length of the information pole (Length) start by bit DA and finished by bit |
| before |  |

FCS.
Length of pole 4-249.
LEr repeating of bit length of the information pole (Length repeat)
DA address of target station (Destination Address)
SA address of supply station (Source Address)
FC drive bit (Frame Control)
DATA pole of dates max 246 bits
FCS control sum (Frame Check Sum)
ED frame end (End Delimiter), code 16H

## LE, LEr - Length of information pole

Both bits in the head of telegram with variable length of information pole contents numbers of bits of information pole. In this is count DA, SA, FC and DATA. Upper value LE is 4, highest 249 . By this possible to transmit 1-246 bits of dates.

## DA, SA - Address of the station (DA - target, SA - supply)

Addresses can be in the range $0-126$, here at the address 127 is use as global address for transmitting of messages for all stations. At setting of global address the instrument receive only (do not transmitting). In the corresponding telegram is the target address (DA) exactly the supply address (SA) from calling telegram.
Limitation: Maximal setting address is 126. Controllers and sensors can not increase the address by bits EXT, how is definite in PROFIBUS.

## FC - Driving bit

Driving bit in the head of frame contents the transmit function and information to prevent for loss or doubling of message.

| b8 | b7 | b6 | b5 | b4 | b3 | b2 | b1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| RES | 1 | FCB | FCV | FUNCTION |  |  |  |
|  | 0 | Stn - Type |  |  |  |  |  |

RES - reservation
b 7 = $\mathbf{1}-$ frame of call (Send / Request)
FCB (Frame Count Bit): $\quad 0 / 1$ - alternated bit of sequence of calls
FCV (Frame Count Bit Valid): 0 - function FCB unvalid
1 - function FCB valid
Controllers and sensors do not use alternating bit FCB at $\mathrm{FCV}=1$, these bits have to have the value $\mathrm{FCB}=1$ and $\mathrm{FCV}=0$.

FUNCTION: frame of call b7 $=1$

| code | function |
| :---: | :--- |
| 0x03 | Send Date with Acknowledge <br> Data sending with acknowledgement |
| $\mathbf{0 x 0 9}$ | Request FDL - Status With Reply <br> Request for Status |
| $\mathbf{0 x 0 C}$ | Send and Request Data <br> Sending and request for dates |

b7 = $\mathbf{0}$ - frame of acknowledgement or answer (Acknowledgement/Response)
Stn - Type (Station type and FDL - STATUS) - to characterise the type of a participant.
Only passive participant $\Rightarrow \mathrm{b} 6$ and $\mathrm{b} 5=0$.
FUNCTION: frame of answer b7 $=0$

| code | function |
| :---: | :--- |
| $\mathbf{0 x 0 0}$ | Acknowledgement positive <br> positive acknowledgement |
| $\mathbf{0 x 0 2}$ | Acknowledgement negative <br> Negative acknowledgement |
| $\mathbf{0 x 0 8}$ | Response FDL / FMA - Date <br> data transmitting |

## FCS - control sum

Control sum is done with arithmetic data sum of information frame DA, SA, FC and DATA module 256 (100h) with ignore of higher ranks creation by transfer 256 ( 100 h ).
$25 \mathrm{~h}=(24 \mathrm{~h}+30 \mathrm{~h}+37 \mathrm{~h}+52 \mathrm{~h}+48 \mathrm{~h})$ MOD 100 h
For SD1 $\sum_{\text {DA }}^{\text {C }} \bmod 256 \quad$ for SD2 $\sum_{\text {DA }}^{\text {FCS-1 }} \bmod 256$

## Format of telegrams with variable length of information pole

Telegram start with SD 2 and $\mathrm{FC}=0 \times 6 \mathrm{C}$. And finish with ending mark ED.
Positive answer is telegram with compact length with $\mathrm{FC}=0$. Negative answer $\mathrm{FC}=2$.


## LAYER 7

Layer 7 (PROFIBUS data part) implement the protocol. There are these services:

1) Reading of the instrument identification
2) Reading of firmware version
3) Reading of a value
4) Record of a value
5) Reading of the instrument state
6) Reading and record of synchronising dates

## 1) Reading of the instrument identification - Identify

telegram SD2 data part
a) request

| SD2 | LE | LEr | SD2 | DA | SA | FC | RI | FCS | ED |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FC |  |  |  |  | 0x6C |  |  |  |  |
| RI |  | REQ_IDENTIFY |  |  | 0x00 |  |  |  |  |

b) answer

| SD2 | LE | LEr | SD2 | DA | SA | FC | DATA | FCS | ED |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |


| FC |  | $0 x 08$ |
| :--- | :--- | :--- |
| DATA | Name type | 21 byte |

2) Reading of firmware - Version telegram SD2 data part
a) request

| SD2 | LE | LEr | SD2 | DA | SA | FC | RV | FCS | ED |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |


| FC |  | $0 \times 6 C$ |
| :--- | :--- | :--- |
| RV | REQ_VERSION | $0 \times 04$ |

b) answer

| SD2 | LE | LEr | SD2 | DA | SA | FC | DATA | FCS | ED |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

FC
0x08
DATA

## 3) Reading of dates - Read

Reading value be determined by chart, numbers of bits and offset.
a) request

| SD2 | LE | LEr | SD2 | DA | SA | FC |  | TC | PB |  | FCS | ED |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FC |  |  |  |  | 0x6 |  |  |  |  |  |  |  |
| RR | REQ_READ |  |  |  | 0x01 |  |  |  |  |  |  |  |
| TC | TABULKA_ČÍSLO |  |  |  | use chart number |  |  |  |  |  |  |  |
| PB | POČET_BYTE |  |  |  | bits in chart |  |  |  |  |  |  |  |
| OF | OFFSET |  |  |  | shift in chart |  |  |  |  |  |  |  |

b) answer

| SD2 | LE | LEr | SD2 | DA | SA | FC | 1 - $\mathbf{n}$ bits by chart | FCS | ED |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

Positive acknowledgement ( $\mathrm{SD} 2, \mathrm{FC}=08$ ), in a case of a failure ( $\mathrm{SD} 1, \mathrm{FC}=2$ ).
$\begin{array}{ll}\text { FC } & 0 x 08 \\ \text { Data } & 1-n \text { bits by chart }\end{array}$

## 4) Record of one value - Write

Recording value be determined by chart, numbers of bits and offset.
a)request

| SD2 | LE | LEr | SD2 | DA | SA | FC | RW | TC | PB OF DT | FCS | ED |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

FC
0x63
RW REQ_WRITE
TC TABULKA_ČÍSLO
PB POČET_BYTE
OF OFFSET
DT DATA

0x02
use chart number
bits in chart
shift in chart
transmit dates $n$ bits (PB bits)
b) answer

Positive acknowledgement ( $\mathrm{SD} 1, \mathrm{FC}=0$ ), in a case of a failure $\mathrm{FC}=2$.

| SD1 | DA | SA | FC | FCS | ED |
| :--- | :--- | :--- | :--- | :--- | :--- |

## 5) Reading of the instrument state

telegram SD2, data part
a) request

| SD2 | LE | LEr | SD2 | DA | SA | FC | RU | FCS | ED |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| FC |  |  |  |  | 0x6 |  |  |  |  |
| RU |  | REQ_Unit_Status |  |  | 0x03 |  |  |  |  |

b) answer

| SD2 | LE | LEr | SD2 | DA | SA | FC | DATA | FCS | ED |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |


| FC |  |
| :--- | :--- |
| DATA | controller state |
|  | 5 bits |


| 4 bit | 1 bits |
| :---: | :---: |
| measured value (float) | OUT (char) |

OUT bit $=0$ output relay is switch-off
OUT bit $=1$ output relay is switch-on
measured value $=$ float format
OUT bit D0 represent output 1
bit D1 represent output 2

## 6) Reading and record of synchronising dates

Telegram SD2, data part.
a) request

| SD2 | LE | LEr | SD2 | DA | SA | FC | RSS | FCS | ED |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |

$\begin{array}{lll}\text { FC } & & 0 \times 63 \\ \text { RSS } & \text { REQ SYNCHRO SAMPLING } & 0 \times 05\end{array}$
b) answer after instruction REQ_SYNCHRO_SAMPLING with FC=0x63 achieve the draft of measured value to buffer. Positive acknowledgements ( $\mathrm{SD} 1, \mathrm{FC}=0$ ), in a case of a failure ( $\mathrm{FC}=2$ ).At using the global address $\mathrm{DA}=127$ is not any answer, the instrument achieve the draft of measured dates only.
c) answer after instruction REQ_SYNCHRO_SAMPLING with FC=0x6C

| SD2 | LE | LEr | SD2 | DA | SA | FC | RES Measured value | FCS | ED |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |


| 1 bit |  | 4 - bits |
| :--- | :--- | :--- |
| RES |  | measured value (float) |
| \# define | FC | 0x08 |
| \#define | RES | $0 \times 01$ indicate first draft |
| \#define | RES | $0 x 00$ indicate, one read dates at least |

## Importance of use symbols

| \# define REQ_IDENTIFY | $0 \times 00$ |
| :--- | :--- |
| \# define REQ_READ | $0 \times 01$ |
| \# define REQ_WRITE | $0 \times 02$ |
| \# define REQ_Unit Status | $0 \times 03$ |
| \# define REQ_VERSION | $0 \times 04$ |
| \# define REQ_SYNCRO_SAMPLING | $0 \times 05$ |

request on the identification request for data sending request for data record request on the instrument state request on the firmware version request on the synchronous draft

Tabulka 1

| Chart _nr. TC = 1 |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Importance | Code | Range | type | Number of <br> bits |  |
| alarm 1 | ALA1 | $-\mathbf{- 9 9 9}$ to 9999 | float | 4 |  |
| alarm 1 | ALA2 | $-\mathbf{- 9 9 9}$ to 9999 | float | 4 |  |
| hysteresis 1 | HYS1 | 0 to 9999 | float | 4 |  |
| output inverting 1 | OUT1 | $0 / 1$ | char | 1 |  |
| output inverting 2 | OUT2 | $0 / 1$ | char | 1 |  |
| relay state at sensor failure | ER-1 / ER-2 | 0x00 /0x01 <br> 0x10 /0x11 | char | 1 |  |
| hysteresis 2 | HYS2 | 0 to 9999 | float | 4 |  |

OUTx
$0=\mathbf{O R}$
ER-1
bit $\mathbf{D 0}=0$ relay 1 off
ER-2
bit D4 $=0$ relay 2 off
$1=\mathbf{N O R}$
bit $\mathbf{D 0}=1$ relay 1 on
bit $\mathbf{D 4}=1$ relay 2 on

Chart 2

| Chart_nr. TC = 2 |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Importance | code | range | type | Number of <br> bits |  |
| Begin of range | STRS | $\mathbf{- 9 9 9}$ to 9999 | float | 4 |  |
| End of range | ENDS | $\mathbf{- 9 9 9}$ to 9999 | float | 4 |  |
| Offset | OFFS | $\mathbf{- 9 9 9}$ to 9999 | float | 4 |  |

Chart 3

| Chart_nr. TC=3 |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| importance | code | range | type | Number of <br> bits |  |
| Type of sensor |  | $0-10$ | char | 1 |  |
| Compensation | COMP | $0-4$ | char | 1 |  |
| Decimal point | _DP | $0-2$ | char | 1 |  |
| Filter | FILT | $0-10$ | char | 1 |  |
| Password | HESL | $-999-9999$ | int | 2 |  |

Sensor type

$$
\begin{array}{ll}
0=\text { thermocouple "J" } & 6=\mathrm{Pt} 100 \\
1=\text { thermocouple "K" } & 7=\text { Ni } 1000 / 6180 \mathrm{ppm} \\
2=\text { thermocouple "E" } & 8=4 \text { to } 20 \mathrm{~mA} \\
3=\text { thermocouple "T" } & 9=0 \text { to } 20 \mathrm{~mA} \\
4=\text { thermocouple ",R" } & 10=0 \text { to } 10 \mathrm{~V} \\
5=\text { thermocouple "S" } &
\end{array}
$$

COM PENSATION $0=$ without compensation
$1=$ temperature of clamps
$2=$ temperature $20^{\circ} \mathrm{C}$
$3=$ temperature $50^{\circ} \mathrm{C}$
$4=$ temperature $70^{\circ} \mathrm{C}$

| $\_$DP_ | 0 <br> 1$=$ number |
| :--- | :--- |
| 2 | $=$ one decimal point |
|  |  |

FILTER $\quad 0=$ no $\quad 1-10=$ yes
Chart 4

| Chart_nr. TC=4 |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| importance | code | range | typ | Number of <br> bits |  |
| Instrument address | - | $0-126$ | char | 1 |  |
|  |  |  |  |  |  |

After setting of the instrument address is the answer with the new address SA.

## Format of dates stored in APOSYS 02

## Signed and Unsigned Characters

Range of char type is 1 bit ( 8 bits).For example value $0 \times 12$

| Address | +0 |
| :---: | :---: |
| Contents | $\mathbf{0 x 1 2}$ |

## Signed and Unsigned Integers

Range of int type is 2 bits ( 16 bits). For example value $0 \times 1234$

| Address | $\mathbf{+ 0}$ | $\mathbf{+ 1}$ |
| :--- | :---: | :---: |
| Contents | $\mathbf{0 x 1 2}$ | $\mathbf{0 x 3 4}$ |

## Signed and Long Integers

Range of long type is 4 bits ( 32 bits). For example value $0 \times 12345678$

| Address | $\mathbf{+ 0}$ | $\mathbf{+ 1}$ | $\mathbf{+ 2}$ | $\mathbf{+ 3}$ |
| :---: | :---: | :---: | :---: | :---: |
| Contents | $\mathbf{0 x 1 2}$ | $\mathbf{0 x 3 4}$ | $\mathbf{0 x 5 6}$ | $\mathbf{0 x 7 8}$ |

## Floating-point Numbers

Range of float type is 4 bits ( 32 bits) by standard IEEE-754

| Address | $\mathbf{+ 0}$ | $\mathbf{+ 1}$ | $\mathbf{+ 2}$ | $\mathbf{+ 3}$ |
| :---: | :---: | :---: | :---: | :---: |
| Contents | SEEE EEEE | EMMM MMMM | MMMM MMMM | MMMM MMMM |

S $\quad$ present mark (1 negative value and 0 positive value)
E "Two's complement exponent" with offset 127
M 23 -bit normal mantissa
Example: value -12,5 is declare hexadecimal $0 \times \mathrm{C} 1480000$

| Address | $\mathbf{+ 0}$ | $\mathbf{+ 1}$ | $\mathbf{+ 2}$ | $\mathbf{+ 3}$ |
| :--- | :---: | :---: | :---: | :---: |
| Contents | $\mathbf{0 x C 1}$ | $\mathbf{0 x 4 8}$ | $\mathbf{0 x 0 0}$ | $\mathbf{0 x 0 0}$ |

Notice:
At first is emit the mark with address (address+0) and last is emit the mark with address (address+n).

## 6. Instructions for software PA 02a installation

### 6.1 Software APOELMOS application

Hardware requirements:
PC: Pentium 100
graphic card: VGA
CD ROM Drive
Software requirements:
MS Windows 95/98/ME and higher versions.
Installation of software suppose the basic knowledge for working with PC and selected instructions MS Windows.

### 6.2 Installation processing:

1) Insert CD ROM to CD ROM drive. If after CD ROM insert to CD ROM drive will start Internet Explorer (autorun) you select from concrete offer „Přístroje" (Apparatuses), „Ukazovací přístroje" (Display apparatuses). Select program for setting of display apparatus APOSYS 02 dates (see. Column - loading / installation sw)
2) On HDD you create a directory
3) Program save to the created directory on HDD.
4) Run file Pa-02a.exe .

### 6.3 Program PA 02a description

1) Introduction
2) First startup
3) Graph setting
4) Data record speed setting
5) Controller parameters setting
6) Controller set parameters saving
7) Data record starting

## 7. Introduction

Software is for controller set parameters and for measured values monitoring.

### 7.1.1 First startup

After software starting you have to set the communication line and the controller address first. In the menu setting you click on the key communication port. The window - communication port is open. At first you set the serial line and communication speed 9600Bd. After that you click on the key - find addresses. In the address chart is displayed the controller address which you enter to the apparatus address. The PC address can be arbitrary in the range from 0 to 126. After setting you confirm by key OK.


### 7.1.2 Graph setting

In the menu setting you click on the key graph setting. The window is open. You set the required range and the time axis of the graph.


### 7.1.3 Data record speed setting

In the menu setting you click on the key - data record speed. The window - data record speed is open. Here you set the required speed of storing to the form and the time of the automatic form storing to the file.


### 7.1.4 Controller parameters setting

In the menu setting you click on the key - controller setting. The window - APOSYS 02 data is open. By the key - parameters reading you can read parameters from the controller. But only parameters which contain the active card. By the key - parameters writing you can write parameters from the active card to the controller. After parameters setting of the controller you click on the key „Parameters writing" for parameters save in the controller in the case of power failure of the controller.


### 7.1.5 Controller set parameters saving

In the window APOSYS 02 you can save the set parameters to the file by the key „Save" (uložit). The file have the suffix txt.


### 7.1.6 Data record starting

In the main window is start and stop of data record starting.


### 7.2 Apparatus connection with PC

Lits converter AMIT 232 TD 495 FD


## 8. ES declaration of comformity

## ES DECLARATION OF COMFORMITY

We,
A.P.O. - ELMOS v.o.s., Pražská 90, 50901 Nová Paka, Czech Republic

## IČO: 60111615

declare on our exclusive responsibility that below mentioned product meet a technical rule requirements that the product is at ours designate application condition secure and that we have taken steps by which we guarantee a comformity of all products below mentioned type be given on market with technical documentation and with requirements of corresponding decree of the government and European guidelines.

Product: Display apparatus APOSYS 02
Type:
Producer:
APOSYS 02
A.P.O. - ELMOS v.o.s.

Pražská 90
50901 Nová Paka
Czech Republic
The product is determined for measuring and control of temperature or the other values.
The product conformity review is made within its borders of the system of product quality review in the copany by the authorized person (nr. AO 201, Elektrotechnický zkušební ústav, Pod lisem 129, Praha 8 - Troja) and execution of inspection over his correct function.

Above mentioned product is with comformity with norms
ČSN EN 61010-1 ed.2:2011 including amendment EN 61010-1:2010 including amendment
ČSN EN 61326-1:2013 including amendment EN 61326-1:2013 including amendment
and decree of the government (European guidelines)
NV 17/2003 Sb. včetně změn
2006/95/EC including amendment
NV 616/2006 Sb. včetně změn
NV 481/2012 Sb. včetně změn
2004/108/EC including amendment
2011/65/EU including amendment
A sample revision achieve a authorized person nr. AO 201, Electrotechnical experimental institute, Pod lisem 129, Praha 8 - Troja, which issue for this product a Certificate nr. 1040416 from day 5.4.2004 and Protocol obout test EMC nr. 4.800385-00 from day 20.4.1999.

The final double-number of the year when the produkt has been labeled with identification CE: 02

| Place of issue: | Nová Paka | Name: | Ing. Libor Lukeš |
| :--- | :--- | :--- | :--- |
| Date of issue: | 22.7 .2014 | Function: | comp. director |

[^0]
## 9. Certificate about the product assembly and quality

## Intelligent display instrument APOSYS 02 prod. no.

## 88-04-08888

We acknowledge that the above mentioned product is complete. And the product answer to technical conditions and is good inspected and tested.

## 10. Guarantee conditions

The producer answers that his product has and will has characters appointed technical norms for appointed time. That is complete and without defects. The producer also answers for defects which a customer find out in the guarantee time and which he claim in the time. The basic conditions of guarantee is the controller using in this way as the above mentioned is in the using handbook.

The guarantee time is 36 months from the date of sale.
The guarantee is possible to apply at material defects or at bad function of the product. Guarantee repairs are achieved with the guarantee rule of the company A.P.O.-ELMOS in the place of business.

The guarantee is dissolved as long as on the product were arrangements achieved or guarantee labels were break down and as long as the product were violently mechanical damage or with wrong using.

Guarantee and after guarantee service perform entirely A.P.O. - ELMOS.

Date of sale:


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[^0]:    APCELMOS
    Stamp: Pražská 90, 50901 Nová Paka DIČ: CZ60111615

    Signature:
    

